

Solvability of Two-Point Boundary Value Problems for Fourth-Order Nonlinear Differential Equations at Resonance

Yuji Liu and Weigao Ge

Abstract. Under a resonance condition involving a two-point boundary value problem for a fourth-order nonlinear differential equation, we show its solvability.

Keywords: *Fourth-order differential equation, two-point boundary value problem, solvability of boundary value problem, resonance*

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1. Introduction

Let $f : [0, 1] \times \mathbb{R}^4$ be a continuous function and $e \in L^1[0, 1]$. We consider the fourth-order differential equation

$$x^{(4)}(t) = f(t, x(t), x'(t), x''(t), x'''(t)) + e(t) \quad (0 < t < 1) \quad (1)$$

subject to the boundary value conditions

$$x'(0) = x'(1) = x'''(0) = x'''(1) = 0. \quad (2)$$

Boundary value problems of this form were used to understand the static equilibrium of an elastic beam supported by sliding clamps. We refer the

Both authors: Beijing Inst. Techn., Dept. Math., Beijing, 100081, P.R. China; the first author also: Hunan Inst. Techn., Dept. Appl. Math., Yueyang, 414000, P.R. China; Liuyuji888@sohu.com

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reader to [11, 12] and the references therein. For example, Gupta [12] studied the solvability of the boundary value problem

$$\left. \begin{aligned} -y^{(4)} + g(t, y(t)) &= e(t) \quad (0 < t < 1) \\ y'(0) = y'(\pi) = y'''(0) &= y'''(\pi) = 0 \end{aligned} \right\}.$$

Since (2) implies that the linear operator $Lx = x^{(4)}$ defined in a suitable Banach space is not invertible, we call (2) a *resonance boundary value condition*. There are many other papers concerning the existence of solutions or positive solutions of fourth-order differential equations subjected to different kind of non-resonance boundary value conditions (see [1 - 6, 8, 10, 13, 14, 16] and the references therein).

To the best of our knowledge, the solvability of boundary value problem (1) - (2) has not been studied till now. The purpose of this paper is to establish an existence result for problem (1) - (2). Our method is based on the coincidence degree theory of Mawhin.

Now, we briefly recall some notations and an abstract existence result. Let X and Y be Banach spaces, $L : \text{dom } L \subset X \rightarrow Y$ be a Fredholm operator of index zero, $P : X \rightarrow X$ and $Q : Y \rightarrow Y$ be projectors such that

$$\begin{aligned} \text{Im } P &= \text{Ker } L \\ \text{Ker } Q &= \text{Im } L \\ X &= \text{Ker } L + \text{Ker } P \\ Y &= \text{Im } L + \text{Im } Q. \end{aligned}$$

It follows that the reduced operator

$$L|_{\text{dom } L \cap \text{Ker } P} : \text{dom } L \cap \text{Ker } P \rightarrow \text{Im } L$$

is invertible. We denote the inverse of that map by K_p .

If Ω is an open bounded subset of X and $\text{dom } L \cap \Omega \neq \emptyset$, where \emptyset denotes the empty set, the map $N : X \rightarrow Y$ will be called *L-compact* on $\overline{\Omega}$ if $QN(\overline{\Omega})$ is bounded and the product map $K_p(I - Q)N : \overline{\Omega} \rightarrow X$ is compact. The facts we use are [15: Theorem 2.4] and [7: Theorem IV.13].

Theorem 1. *Let L be a Fredholm operator of index zero and let N be L -compact on Ω . Assume that the following conditions are satisfied:*

- (i) $Lx \neq \lambda Nx$ for every $(x, \lambda) \in [(\text{dom } L / \text{Ker } L) \cap \partial\Omega] \times (0, 1)$.
- (ii) $Nx \notin \text{Im } L$ for every $x \in \text{Ker } L \cap \partial\Omega$.
- (iii) $\text{deg}(\Lambda QN|_{\text{Ker } L}, \Omega \cap \text{Ker } L, 0) \neq 0$, where $\Lambda : \text{Im } L \rightarrow \text{Ker } L$ is some isomorphism.

Then the equation $Lx = Nx$ has at least one solution in $\text{dom } L \cap \overline{\Omega}$.

We use the classical spaces $C^3[0, 1]$ and $L^1[0, 1]$. For $x \in C^3[0, 1]$, we use the norms $\|x\|_\infty = \max_{t \in [0, 1]} |x(t)|$ and

$$\|x\| = \max \{ \|x\|_\infty, \|x'\|_\infty, \|x''\|_\infty, \|x'''\|_\infty \}$$

and denote the norm in $L^1[0, 1]$ by $\|x\|_1$. We also use the Sobolev space $W^{4,1}(0, 1)$ defined by

$$W^{4,1} = \left\{ x : [0, 1] \rightarrow \mathbb{R} \mid x, x', x'', x''' \text{ abs. cont., } x^{(4)} \in L^1[0, 1] \right\}$$

with its usual norm.

2. Main results

In this section, we shall prove the existence result for problem (1) - (2). Let $X = C^3[0, 1]$ and $Y = L^1[0, 1]$. Define L to be the linear operator from $\text{dom } L \subset X$ to Y with

$$\text{dom } L = \left\{ x \in W^{4,1}(0, 1) \mid x'(0) = x'(1) = x'''(0) = x'''(1) = 0 \right\}$$

and $(Lx)(t) = x^{(4)}(t)$ for $x \in \text{dom } L \cap X$, and we define N to be the nonlinear operator from X to Y with

$$(Nx)(t) = f(t, x(t), x'(t), x''(t), x'''(t)) + e(t) \quad (0 < t < 1)$$

for $x \in X$. Thus problem (1) - (2) can be written as $Lx = Nx$. We note that if $x \in \text{dom } L$, then $\|x\| = \max\{\|x\|_\infty, \|x'''\|_\infty\}$, since $\|x'\|_\infty \leq \|x''\|_\infty \leq \|x'''\|_\infty$.

Lemma 1. *The following results hold:*

(i) $\text{Ker } L = \{x \in X : x(t) = c \quad (0 \leq t \leq 1) \text{ for some } c \in \mathbb{R}\}$.

(ii) $\text{Im } L = \{y \in Y : \int_0^1 y(s) ds = 0\}$.

(iii) L is a Fredholm operator of index zero.

(iv) If Ω is an open bounded subset such that $\text{dom } L \cap \Omega \neq \emptyset$, then N is L -compact on $\overline{\Omega}$.

Proof. (i): For $x \in \text{Ker } L$ we have $x^{(4)}(t) = 0$, thus $x(t) = at^3 + bt^2 + ct + d$. On the other hand, $x'(0) = x'(1) = x'''(0) = x'''(1) = 0$ implies that $a = b = c = 0$. So $x(t) = d$ for $t \in [0, 1]$. Again, if $x = d$, then $x \in \text{Ker } L$. This completes the proof of assertion (i).

(ii): For $y \in \text{Im } L$ there is $x \in \text{dom } L$ such that $x^{(4)} = y$. So

$$x(t) = \int_0^t \frac{(t-s)^3}{6} y(s) ds + at^3 + bt^2 + ct + d.$$

Since $x'(0) = x'(1) = x'''(1) = x'''(0) = 0$, we get $c = a = 0$ and $\int_0^1 y(s) ds = 0$. Thus $y \in \{y \in Y : \int_0^1 y(s) ds = 0\}$. On the other hand, if $y \in Y$ and $\int_0^1 y(s) ds = 0$, let

$$x(t) = \int_0^t \frac{(t-s)^3}{6} y(s) ds - \frac{t^2}{2} \int_0^1 \frac{(1-s)^2}{2} y(s) ds.$$

Then $x \in X$ and $x'(0) = x'(1) = x'''(0) = x'''(1) = 0$. This implies $y \in \text{Im } L$, so assertion (ii) is valid.

(iii): Define the projector $Q : Y \rightarrow Y$ by

$$Qy(t) = \int_0^1 y(s) ds \quad (y \in Y).$$

It is easy to check that, for $y \in Y$, $y - Qy \in \text{Im } L$. So $y = \text{Im } L + R$, again $\text{Im } L \cap R = \{0\}$, hence $Y = \text{Im } L \oplus R$. Together with that $\text{Im } L$ is closed, thus L is a Fredholm operator of index zero.

(iv) Let Ω be an open bounded subset in X such that $\Omega \cap \text{dom } L \neq \Phi$. Define the projector $P : X \rightarrow X$ by $P(x) = x(0)$. Then the generalized inverse $K_p : \text{Im } L \rightarrow \text{dom } L \cap \text{Ker } P$ of L can be written as

$$(K_p y)(t) = \int_0^t \frac{(t-s)^3}{6} y(s) ds - \frac{t^2}{2} \int_0^1 \frac{(1-s)^2}{2} y(s) ds. \tag{4}$$

In fact, for $y \in \text{Im } L$ we have

$$(LK_p)y(t) = L \left(\int_0^t \frac{(t-s)^3}{6} y(s) ds - \frac{t^2}{2} \int_0^1 \frac{(1-s)^2}{2} y(s) ds \right) = y(t).$$

Further, for $x \in \text{dom } L \cap \text{Ker } P$ we have

$$\begin{aligned} (K_p Lx)(t) &= K_p(x^{(4)}(t)) \\ &= \int_0^t \frac{(t-s)^3}{6} x^{(4)}(s) ds - \frac{t^2}{2} \int_0^1 \frac{(1-s)^2}{2} x^{(4)}(s) ds \\ &= \frac{t^3}{6} x'''(0) + \frac{t^2}{2} x''(0) + tx'(0) + x(t) - x(0) - \frac{t^2}{2} x''(0) \\ &= x(t). \end{aligned}$$

This shows $K_p = (L|_{\text{dom } L \cap \text{Ker } P})^{-1}$. Furthermore, $X = \text{Ker } L \oplus \text{Ker } P$. In fact, for $x \in X$, $x(t) - x(0) \in \text{Ker } P$, so $X = \text{Ker } P + \text{Ker } L$, and again $\text{Ker } L \cap \text{Ker } P = \{0\}$. Then $X = \text{Ker } L \oplus \text{Ker } P$. From (4) we find

$$\begin{aligned} \|K_p y\|_\infty &\leq \frac{1}{6}\|y\|_1 + \frac{1}{4}\|y\|_1 = \frac{5}{12}\|y\|_1 \\ \|(K_p y)'\|_\infty &\leq \frac{1}{2}\|y\|_1 + \frac{1}{2}\|y\|_1 = \|y\|_1 \\ \|(K_p y)'''\|_\infty &= \left\| \int_0^t y(s) ds \right\|_\infty \leq \|y\|_1. \end{aligned}$$

Since $(K_p y)'(0) = (K_p y)'(1) = 0$, there is $\xi \in (0, 1)$ such that $(K_p y)''(\xi) = 0$. Hence for $t \in (0, 1)$ we have

$$\begin{aligned} |(K_p y)''(t)| &= |(K_p y)''(t) - (K_p y)''(\xi)| \\ &= |(K_p y)'''(\eta)(t - \xi)| \\ &\leq |(K_p y)'''(\eta)| \end{aligned}$$

for $\eta \in (t, \xi)$ or $\eta \in (\xi, t)$. So

$$\|(K_p y)''\|_\infty \leq \|(K_p y)'''\|_\infty \leq \|y\|_1.$$

It follows that $\|K_p y\| \leq \|y\|_1$ for $y \in Y$. It is easy to see that

$$(QNx)(t) = \int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds$$

and

$$\begin{aligned} &K_p(I - Q)Nx(t) \\ &= \int_0^t \frac{(t - s)^3}{6} \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds \\ &\quad - \frac{t^2}{2} \int_0^1 \frac{(1 - s)^2}{2} \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds \\ &\quad - \left(\frac{t^4}{24} + \frac{t^2}{12} \right) \int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds. \end{aligned}$$

By using the Ascoli-Arzelà theorem, we can prove that $QN(\overline{\Omega})$ is bounded and $K_p(I - Q)N : \overline{\Omega} \rightarrow X$ is compact. So N is L -compact on $\overline{\Omega}$ ■

Theorem 2. Let $f : [0, 1] \times R^4 \rightarrow R$ be a continuous function. Assume the following:

(A₁) There exist functions $a, b, c, d, g : [0, 1] \rightarrow \mathbb{R}$ and $r \in L^1[0, 1]$ and a constant $\theta \in [0, 1)$ such that

$$|f(t, x, y, z, w)| \leq a(t)|x| + b(t)|y| + c(t)|z| + d(t)|w| + g(t)|w|^\theta + r(t);$$

for all $t \in [0, 1]$.

(A₂) There exists a constant $M > 0$ such that if $|w| > M$, then

$$|f(t, x, y, z, w)| > -\bar{\alpha}|x| + \bar{\beta}|w| - L_1$$

for all $x, y, z \in R$ and $t \in [0, 1]$, where $\bar{\beta} > \bar{\alpha} > 0$ and $L_1 > 0$ are some constants.

(A₃) There is a constant $M_1 > 0$ such that if $|x(t)| > M_1$ for all $t \in [0, 1]$, then

$$\int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds \neq 0.$$

(A₄) $\lim_{|c| \rightarrow \infty} \frac{|f(t, c, 0, 0, 0)|}{|c|} \in (0, +\infty)$.

(A₅) There is a constant $M_2 > 0$ such that if $|c| > M_2$, then

$$cf(t, c, 0, 0, 0) \begin{cases} \leq 0 \\ \text{or} \\ \geq 0 \end{cases} \quad (0 \leq t \leq 1).$$

(A₆) $\|a\|_1 + \|b\|_1 + \|c\|_1 + \|d\|_1 < \frac{1}{2} \left(1 - \frac{\bar{\alpha}}{\bar{\beta}} \right)$.

Then for every $e \in L^1[0, 1]$ problem (1) – (2) has at least one solution in $C^3[0, 1]$.

Proof. Let

$$\Omega_1 = \left\{ x \in \text{dom } L / \text{Ker } L : Lx = \lambda Nx \text{ for some } \lambda \in (0, 1) \right\}.$$

If $x \in \Omega_1$, then $x \notin \text{Ker } L$, $\lambda \neq 0$ and $Nx \in \text{Im } L$, thus $QNx = 0$, i.e.

$$x^{(4)}(t) = \lambda f(t, x(t), x'(t), x''(t), x'''(t)) + e(t) \quad (t \in [0, 1])$$

$$x'(0) = x'(1) = x'''(0) = x'''(1) = 0$$

$$\int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds = 0.$$

So there is $t_1 \in (0, 1)$ such that

$$f(t_1, x(t_1), x'(t_1), x''(t_1), x'''(t_1)) = - \int_0^1 e(s) ds.$$

This yields

$$|f(t_1, x(t_1), x'(t_1), x''(t_1), x'''(t_1))| \leq \|e\|_1.$$

Again, if $x \in \text{dom } L$, then $(I - P)x \in \text{dom } L \cap \text{Ker } P$ and $LPx = 0$. Thus, from Lemma 1,

$$\|(I - P)x\| = \|K_p L(I - P)x\| \leq \|L(I - P)x\|_1 = \|Lx\|_1 \leq \|Nx\|_1.$$

We consider two cases.

Case 1: $|x'''(t^*)| \leq M$ for some $t^* \in [0, 1]$. In this case we have

$$|x'''(t)| = |x'''(t^*)| + \left| \int_t^{t^*} x^{(4)}(s) ds \right| \leq M + \|Lx\|_1 \leq M + \|Nx\|_1.$$

Since $x'(0) = x'(1) = x'''(0) = x'''(1) = 0$, there is $\xi \in (0, 1)$ such that $x''(\xi) = 0$, thus

$$|x''(t)| = |x''(t) - x''(\xi)| = |x'''(\eta)(t - \xi)| \leq M + \|Nx\|_1.$$

Also, there is $\eta_1 \in [0, 1]$ such that

$$|x'(t)| = |x'(t) - x'(0)| = |x''(\eta_1)t| \leq M + \|Nx\|_1.$$

We claim that there is a $t^{**} \in (0, 1)$ such that $|x(t^{**})| \leq M_1$. Otherwise, if $|x(t)| > M_1$ for all $t \in [0, 1]$, condition (A₃) implies

$$\int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds \neq 0.$$

On the other hand, since $Lx \in \text{Im } L$, we have

$$\int_0^1 \left(f(s, x(s), x'(s), x''(s), x'''(s)) + e(s) \right) ds = 0,$$

which is a contradiction. Thus

$$|x(0)| = |x(t^{**})| + \left| \int_0^{t^{**}} x'(s) ds \right| \leq M_1 + M + \|Nx\|_1.$$

Hence

$$\|Px\| = |x(0)| \leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \|Nx\|_1 + c_1$$

where

$$c_1 = \max \left\{ M_1 + M, M_1 + \frac{1}{\beta} (L_1 + \|e\|_1) \right\}.$$

Thus we get

$$\|x\| \leq \|Px\| + \|(I - P)x\| \leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + 2\|Nx\|_1 + c_1.$$

From Property (A₁) we get

$$\begin{aligned} \|x\| &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + 2\|a\|_1 \|x\|_\infty + 2\|b\|_1 \|x'\|_\infty + 2\|c\|_1 \|x''\|_\infty \\ &\quad + 2\|d\|_1 \|x'''\|_\infty + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \\ &= \left(2\|a\|_1 + \frac{\bar{\alpha}}{\beta}\right) \|x\|_\infty + 2\|b\|_1 \|x'\|_\infty + 2\|c\|_1 \|x''\|_\infty \\ &\quad + 2\|d\|_1 \|x'''\|_\infty + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \\ &\leq \left(2\|a\|_1 + \frac{\bar{\alpha}}{\beta}\right) \|x\|_\infty + (2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty \\ &\quad + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1, \end{aligned}$$

i.e.

$$\begin{aligned} \|x\| &\leq \left(2\|a\|_1 + \frac{\bar{\alpha}}{\beta}\right) \|x\|_\infty + (2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty \\ &\quad + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1. \end{aligned}$$

It is easy to check that $\|x'\|_\infty \leq \|x''\|_\infty \leq \|x'''\|_\infty$. Together with $\|x\|_\infty \leq \|x\|$, it follows from the above inequality that

$$\begin{aligned} \|x\|_\infty &\leq \frac{1}{1 - 2\|a\|_1 - \frac{\bar{\alpha}}{\beta}} \left[2\|b\|_1 \|x'\|_\infty + 2\|c\|_1 \|x''\|_\infty \right. \\ &\quad \left. + 2\|d\|_1 \|x'''\|_\infty + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \right] \\ &\leq \frac{1}{1 - 2\|a\|_1 - \frac{\bar{\alpha}}{\beta}} \left[(2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty \right. \\ &\quad \left. + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \right]. \end{aligned} \tag{5}$$

Case 2. $|x'''(t)| > M$ for all $t \in [0, 1]$. In this case from property (A₂) we obtain

$$\begin{aligned} |x'''(t_1)| &\leq \frac{\bar{\alpha}}{\beta} |x(t_1)| + \frac{L_1}{\beta} + \frac{1}{\beta} |f(t_1, x(t_1), x'(t_1), x''(t_1), x'''(t_1))| \\ &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \frac{1}{\beta} (L_1 + \|e\|_1) \end{aligned}$$

so that

$$\begin{aligned} |x'''(t)| &\leq |x'''(t_1)| + \left| \int_{t_1}^t x^{(4)}(s) ds \right| \\ &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \frac{1}{\beta} (L_1 + \|e\|_1) + \|Nx\|_1. \end{aligned}$$

Thus similarly to the above discussion, one has a $\xi \in (0, 1)$ such that $x''(\xi) = 0$ and there is an $\eta \in (0, 1)$ such that

$$\begin{aligned} |x''(t)| &= |x''(t) - x''(\xi)| \\ &= |x'''(\eta)(t - \eta)| \\ &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \frac{1}{\beta} (L_1 + \|e\|_1) + \|Nx\|_1. \end{aligned}$$

So we get

$$\begin{aligned} |x'(t)| &= |x'(t) - x'(0)| \\ &\leq |x''(\xi)| \\ &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \frac{1}{\beta} (L_1 + \|e\|_1) + \|Nx\|_1. \end{aligned}$$

From property (A₃), there is a $t^{**} \in (0, 1)$ such that $|x(t^{**})| \leq M_1$. Then, together with (5),

$$\begin{aligned} \|Px\| &= |x(0)| \\ &= \left| x(t^{**}) - \int_0^{t^{**}} x'(t) dt \right| \\ &\leq M_1 + \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \frac{1}{\beta} (L_1 + \|e\|_1) + \|Nx\|_1 \\ &\leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + \|Nx\|_1 + c_1. \end{aligned}$$

Thus

$$\|x\| \leq \|Px\| + \|(I - P)x\| \leq \frac{\bar{\alpha}}{\beta} \|x\|_\infty + 2\|Nx\|_1 + c_1.$$

So property (A₁) implies

$$\begin{aligned} \|x'''\|_\infty &\leq \|x\| \\ &\leq \frac{2\|a\|_1 + \frac{\bar{\alpha}}{\beta}}{1 - 2\|a\|_1 - \frac{\bar{\alpha}}{\beta}} \left[(2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty \right. \\ &\quad \left. + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \right] \\ &\quad + \left[(2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty \right. \\ &\quad \left. + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \right] \end{aligned}$$

$$= \frac{1}{1 - 2\|a\|_1 - \frac{\bar{\alpha}}{\beta}} \left[(2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1) \|x'''\|_\infty + 2\|g\|_1 \|x'''\|_\infty^\theta + 2\|r\|_1 + 2\|e\|_1 + c_1 \right].$$

We get (5). From (5) it follows that

$$\|x'''\|_\infty \leq \frac{2\|g\|_1 \|x'''\|_\infty^\theta + c_1 + 2\|r\|_1 + 2\|e\|_1}{1 - 2\|a\|_1 + 2\|b\|_1 + 2\|c\|_1 + 2\|d\|_1 - \frac{\bar{\alpha}}{\beta}} \left(1 - 2\|a\|_1 - \frac{\bar{\alpha}}{\beta}\right).$$

Since $\theta \in [0, 1]$, there is $M_1^* > 0$ such that

$$\|x'''\|_\infty \leq M_1^*.$$

Again, it is easy to prove that

$$\left. \begin{aligned} \|x''\|_\infty &\leq \|x'''\|_\infty \\ \|x'\|_\infty &\leq \|x''\|_\infty \leq \|x'''\|_\infty \end{aligned} \right\} \leq M_1^*.$$

From property (A₃) we claim that there is $t^{**} \in (0, 1)$ such that $|x(t^{**})| \leq M_1$. Thus

$$|x(t)| \leq \left| x(t^{**}) - \int_t^{t^{**}} x'(s) ds \right| \leq M_1 + \|x'\|_\infty.$$

Hence there is $M_2^* > 0$ such that $\|x\|_\infty \leq M_2^*$. Hence

$$\|x\| \leq \max \{ \|x\|_\infty, \|x'\|_\infty, \|x''\|_\infty, \|x'''\|_\infty \} \leq \max \{ M_1^*, M_2^* \}.$$

Thus Ω_1 is bounded. Let

$$\Omega_2 = \{ x \in \text{Ker } L : Nx \in \text{Im } L \}.$$

For $x \in \Omega_2$, $x \in \text{Ker } L$ and $QNx = 0$, thus

$$\int_0^1 (f(s, c, 0, 0, 0) + e(s)) ds = 0, \quad \text{i.e.} \quad \int_0^1 f(s, c, 0, 0, 0) ds = - \int_0^1 e(s) ds.$$

Thus there is $t_0 \in (0, 1)$ such that

$$f(t_0, c, 0, 0, 0) = - \int_0^1 e(s) ds, \quad \text{so} \quad |f(t_0, c, 0, 0, 0)| \leq \|e\|_1.$$

From property (A₄) we see that there is $M^* > 0$ such that $|c| \leq M^*$. Thus Ω_2 is bounded. Next, according condition (A₅), we have the following two cases.

Case 1. Suppose for any $c \in R$, if $|c| > M_2$, then $cf(t, c, 0, 0, 0) \leq 0$ for $t \in [0, 1]$. Let

$$\Omega_3 = \left\{ x \in \text{Ker } L : -\lambda x + (1 - \lambda)QNx = 0, \lambda \in [0, 1] \right\}.$$

Now, similar to the proof of [6: Lemma 2.12], we prove that Ω_3 is bounded. Suppose $x_n(t) = c_n \in \Omega_3$ and $|c_n| \rightarrow \infty$ as $n \rightarrow \infty$. Without loss of generality, suppose that $c_n > M_2$ for all n . Then there is $\lambda_n \in [0, 1]$ such that

$$\lambda_n c_n = (1 - \lambda_n)QN(c_n), \quad \text{or } \lambda_n = (1 - \lambda_n) \frac{QN(c_n)}{c_n}. \quad (6)$$

Without loss of generality, suppose $\lambda_n \rightarrow \lambda_0$ as $n \rightarrow \infty$. Then

$$\begin{aligned} \left| \frac{QN(c_n)}{c_n} \right| &= \frac{1}{|c_n|} \left| \int_0^1 (f(s, c_n, 0, 0, 0) + e(s)) ds \right| \\ &\leq \frac{1}{|c_n|} [\|e\|_1 + \|a\|_1 |c_n| + \|r\|_1] \\ &= \|a\|_1 + \frac{\|e\|_1 + \|r\|_1}{|c_n|}. \end{aligned}$$

Thus $\frac{|QN(c_n)|}{|c_n|}$ is bounded. So $\lambda_n \rightarrow \lambda_0 \neq 1$ by (6). Thus, for sufficiently large n , $\lambda_n \neq 1$. Then

$$\frac{\lambda_n}{1 - \lambda_n} = \frac{1}{c_n} \left(\int_0^1 (f(s, c_n, 0, 0, 0) + e(s)) ds \right).$$

From property (A₄), for sufficiently large n , $|f(t, c_n, 0, 0, 0)| \geq \alpha|c_n|$ for some $\alpha > 0$. Then property (A₅) implies $f(t, c_n, 0, 0, 0) < -\alpha c_n$. Thus, by Fatou's Lemma,

$$\begin{aligned} &\limsup \left(\frac{1}{c_n} \int_0^1 f(s, c_n, 0, 0, 0) ds + \frac{1}{c_n} \int_0^1 e(s) ds \right) \\ &\leq \limsup \frac{1}{c_n} \int_0^1 f(s, c_n, 0, 0, 0) ds \\ &\leq \int_0^1 \limsup \frac{f(s, c_n, 0, 0, 0)}{c_n} ds \\ &\leq -\alpha \\ &< 0. \end{aligned}$$

This contradicts $\frac{\lambda_n}{1 - \lambda_n} \geq 0$. Then Ω_3 is bounded.

Case 2. Suppose $|c| > M_2$. Then $cf(t, c, 0, 0, 0) \geq 0$ for $t \in [0, 1]$. Indeed, set

$$\Omega_3 = \left\{ x \in \text{Ker } L : \lambda x + (1 - \lambda)QNx = 0 \text{ for all } \lambda \in (0, 1) \right\}.$$

Like in the above argument, we can prove that Ω_3 is bounded. In the following, we shall prove that all conditions of Theorem 1 are satisfied. Let Ω be a bounded open subset of X such that

$$\sqcup_{i=1}^3 \overline{\Omega}_i \subset \Omega.$$

By Lemma 1, L is a Fredholm operator of index zero and N is L -compact on $\overline{\Omega}$. By the above argument and the definition of Ω , we have:

- (i) $Lx \neq \lambda Nx$ for $(\lambda, x) \in [(\text{dom } L/\text{Ker } L) \cap \partial\Omega] \times (0, 1)$
- (ii) $Nx \notin \text{Im } L$ for $x \in \text{Ker } L \cap \partial\Omega$.

At last, we prove that condition (iii) of Theorem M is satisfied. Let

$$H(x, \lambda) = \pm \lambda x + (1 - \lambda)QNx.$$

By the definition of Ω , we see that $H(x, \lambda) \neq 0$ for $x \in \partial\Omega \cap \text{Ker } L$. Thus, by the homotopy property of degree, we have

$$\begin{aligned} \deg(QN_{\text{Ker } L}, \Omega \cap \text{Ker } L, 0) &= \deg(H(\cdot, 0), \Omega \cap \text{Ker } L, 0) \\ &= \deg(H(\cdot, 1), \Omega \cap \text{Ker } L, 0) \\ &= \deg(\pm \lambda I, \Omega \cap \text{Ker } L, 0) \\ &\neq 0. \end{aligned}$$

Thus by Theorem 1, the equation $Lx = Nx$ has at least one solution in $\text{dom } L \cap \overline{\Omega}$. So problem (1) - (2) has at least one solution ■

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