# $L_{\varphi}$-Spaces and some Related Sequence Spaces 

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#### Abstract

In view of closed graph theorems in case of maps defined by operator-valued matrices $L_{\varphi}$-spaces were recently introduced by two of the present authors as a generalization of separable $F K(X)$-spaces. In this paper we study the class of $L_{\varphi}$-spaces and a few closely related classes of sequence spaces. It is shown that an analogue of Kalton's closed graph theorem holds for matrix mappings if we consider $L_{\varphi}$-spaces as range spaces, and paralleling a result of Qiu we prove that the class of $L_{\varphi}$-spaces is the best-possible choice here. As a consequence we show that for any $L_{\varphi}$-space $E$ every matrix domain $E_{A}$ is again an $L_{\varphi}$-space.


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## 1. Introduction

Let $E$ and $F$ be locally convex spaces and suppose that $E$ is a Mackey space, the space ( $E^{\prime}, \sigma\left(E^{\prime}, E\right)$ ) is sequentially complete and $F$ is separable and $B_{r}$-complete. Then Kalton's closed graph theorem [10] states that every closed linear map $T: E \longrightarrow F$ is continuous. Subsequently, Qiu [11] has identified the maximal class of range spaces $F$ in this result, calling its elements $L_{r}$-spaces.

Kalton's theorem was successfully applied in classical summability theory to obtain inclusion theorems for $K$-spaces that are important in connection with Mazur-Orlicztype theorems (cf. [2-4]). In these applications $F$ is a convergence domain $c_{A}$ of some matrix $A$, which is always a separable Fréchet space. However, if one tries to extend these results to operator-valued matrices one encounters the problem that convergence domains are no longer separable in general. In fact they need not even be $L_{r}$-spaces [ 8 : Example 3.13/(b)].

[^0]Thus a new idea was needed. Now, in summability theory one usually deals with matrix mappings between sequence spaces, which ordinarily are particular closed mappings. In a recent paper two of the present authors were able to show that if we only consider matrix mappings, then a Kalton-type result obtains for all spaces $F$ from a new class of spaces, which they call $L_{\varphi}$-spaces (see [8: Theorem 4.2]). As desired, this class is large enough to contain all convergence domains of'operator-valued matrices, so that one can now deduce inclusion theorems for such matrices [8: Theorem 4.4].

In this paper we study the class of ' $L_{\varphi}$-spaces and a few closely related classes of sequence spaces. We show that, indeed, Kalton's theorem and Qiu's characterization hold for $L_{\varphi}$-spaces if closed mappings are replaced by matrix mappings. It is also shown that for every $L_{\varphi}$-space $E$ any matrix domain $E_{A}$ is again an $L_{\varphi}$-space, answering a question in [8]. Similar results are proved for the other classes of sequence spaces considered here. For further investigations into $L_{\varphi}$-spaces see [6].

## 2. Notations and preliminaries

Throughout this paper we assume that $\left(X, \tau_{X}\right)$ and ( $Y, \tau_{Y}$ ) are (locally convex) Fréchet spaces. A sequence space (over $X$ ) is a subspace of the space $\omega(X)$ of all sequences $x=\left(x_{k}\right)$ in $X$. In particular, $c(X)$ and $\varphi(X)$ denote the spaces of convergent and finite sequences in $X$, respectively. The $\beta$-dual $E^{\beta}$ of a sequence space $E$ over $X$ is defined as

$$
E^{\beta}=\left\{\left(A_{k}\right) \in \omega\left(X^{\prime}\right) \mid \forall\left(x_{k}\right) \in E: \sum_{k} A_{k}\left(x_{k}\right) \text { converges }\right\} .
$$

Now suppose that the sequence space $E$ over $X$ is endowed with a locally convex topology $\tau$. Then $E$ is called a $K(X)$-space if the inclusion map $i: E \longrightarrow \omega(X)$ is continuous, where $\omega(X)$ carries the product topology. If, in addition, $(E, \tau)$ is a Fréchet (Banach) space, then $E$ is called an $F K(X)$-space $(B K(X)$-space). A $K(X)$-space $E$ is called an $A K$-space ( $S A K$-space) if ( $x_{1}, \ldots, x_{n}, 0, \ldots$ ) $\longrightarrow x$ (weakly) in $E$ as $n \longrightarrow \infty$ for all $x \doteq\left(x_{k}\right) \in E$. If $E$ is a $K(X)$-space, then every element $\left(A_{k}\right) \in E^{\beta}$ defines a linear functional on $E$ via $\left(x_{k}\right) \longrightarrow \sum_{k} A_{k}\left(x_{k}\right)$. Hence, as usual, we can consider $E^{\beta}$ as a subspace of $E^{*}$, the algebraic dual of $E$. In particular we have $\varphi\left(X^{\prime}\right) \subset E^{*}$.

Let $A=\left(A_{n k}\right)$ be a matrix with entries $A_{n k} \in B(X, Y)$, i.e., continuous linear operators $A_{n k}: X \longrightarrow Y$. A is called row-finite if each sequence $\left(A_{n k}\right)_{k}(n \in \mathbb{N})$ is finite. For a sequence space $E$ over $Y$ the matrix domain $E_{A}$ is defined as

$$
E_{A}=\left\{x \in \omega(X) \mid \forall n \in \mathbb{N}: \sum_{k} A_{n k}\left(x_{k}\right) \text { converges and }\left(\sum_{k} A_{n k}\left(x_{k}\right)\right)_{n} \in E\right\}
$$

Here, the convergence of $\sum_{k} A_{n k}\left(x_{k}\right)$ is taken in the topology $\tau_{Y}$. If, instead, we only require convergence with respect to $\sigma\left(Y, Y^{\prime}\right)$, then the corresponding sequence space is called a weak matrix domain, denoted by $E_{A_{w}}$. For any $x \in E_{A_{w}}$ we put $A x:=$ $\left(\sum_{k} A_{n k}\left(x_{k}\right)\right)_{n}$. If $F$ is a sequence space over $X$ with $F \subset E_{A}\left(F \subset E_{A_{w}}\right)$, then the
mapping $A: F \longrightarrow E, x \longrightarrow A x$, is called a (weak) matrix mapping. The space $\omega(Y)_{A}$ is an $F K(X)$-space by [5: Theorem 2.14], and the matrix domain $E_{A}$ becomes an $\dot{F} K(X)$ space when it is endowed with the strongest topology that makes the matrix mappings $A: E_{A} \longrightarrow E, x \longrightarrow A x$ and $i: E_{A} \longrightarrow \omega(Y)_{A}, x \longrightarrow x$ continuous [1: Proposition 2.4].

The terminology from the theory of locally convex spaces is standard. We follow Wilansky [12]. For the theory of $F K(X)$-spaces and operator-valued matrix domains we refer to [1] and [5].

## 3. $L_{\varphi}-K$-spaces and some related $K$-spaces

Let $(E, \tau)$ be a locally convex space with topological dual $E^{\prime}$ and algebraic dual $E^{*}$. For any subspace $S$ of $E^{*}, S<E^{*}$, we use the notations

$$
\begin{aligned}
& \stackrel{\urcorner}{S}:=\left\{g \in E^{*} \mid \exists\left(g_{n}\right) \text { in } S: g_{n} \xrightarrow{!} g\left(\sigma\left(E^{*}, E\right)\right)\right\} \\
& \stackrel{\zeta}{S}:=\cap\left\{V<E^{*} \mid S \subset V=\stackrel{\Im}{V}\right\} \\
& \Gamma^{1}:=\nabla_{S} \quad \text { and } \quad \Gamma^{j+1}:=\nabla^{i}{ }^{1}=\nabla^{j} \cap E^{\prime} \quad(j \in \mathbb{N}) \text {. }
\end{aligned}
$$

Following J. Qiu [11] we define $E$ to be an $L_{r}$-space if $E^{\prime} \subset S$ for any $\sigma\left(E^{\prime}, E\right)$-dense subspace $S$ of $E^{\prime}$.

In case of $K(X)$-spaces $E$ we note that $\varphi\left(X^{\prime}\right)$ is $\sigma\left(E^{\prime}, E\right)$-dense in $E^{\prime}$ [8: Theorem 3.4] and introduce the following notations (see also [8]).

Definition and Remarks 3.1. Let $E$ be a $K(X)$-space and $j \in \mathbb{N} . E$ is called an

$$
\begin{aligned}
& L_{\varphi} \text {-space if } E^{\prime} \subset \varphi\left(X^{\prime}\right) \\
& L_{\varphi}(j) \text {-space if } E^{\prime} \subset{\overleftarrow{\varphi\left(X^{\prime}\right)}}^{j} \\
& L_{\beta}(j) \text {-space if } E^{\prime} \subset{E^{\beta}}
\end{aligned}
$$

In [8] $L_{\varphi}(1)$-spaces and $L_{\beta}(1)$-spaces are called spaces having $\varphi$-sequentially dense dual and $\beta$-sequentially dense dual, respectively.
$E$ is an $L_{\varphi}$-space if and only if $E^{\prime} \subset E^{\beta}$ since $E^{\beta} \subset \varphi\left(X^{\prime}\right)$. In fact, we even have $E^{\beta} \subset \overleftarrow{\varphi\left(X^{\prime}\right)}$.

The above definitions depend only on the dual pair ( $E, E^{\prime}$ ) and not on the particular topology compatible with this dual pair. Obviously, for each $j \in \mathbb{N}$ we have

$$
L_{\varphi}(j) \text {-space } \Rightarrow L_{\mathcal{\beta}}(j) \text {-space } \Rightarrow L_{\varphi}(j+1) \text {-space } \Rightarrow L_{\varphi} \text {-space } \Leftarrow L_{r} \text {-space }
$$

Remarks 3.2. Let $E$ be any sequence space over $X$ and let $H$ with $\varphi\left(X^{\prime}\right)<H<$ $\stackrel{E^{\beta}}{ }$ be given.
(a) Then ( $E, \tau(E, H)$ ) is an $L_{\varphi}$-space. (The proof of the Inclusion Theorem in [7] shows us that we may be interested in $L_{\varphi}$-spaces $(E, \tau(E, H)$ ) where $H$ is a very small subspace of $\stackrel{-}{E^{\beta}}$ containing $\varphi\left(X^{\prime}\right)$.)
(b) The statement in (a) remains true for any topology $\tau$ (instead of $\tau(E, H)$ ) that is compatible with the dual pair $(E, H)$.
(c) Obviously, $\tau\left(E, \mathbb{E}^{\boldsymbol{\beta}}\right)$ is the strongest locally convex topology $\tau$ such that $(E, \tau)$ is an $L_{\varphi}$-space.
(d) If $j \in \mathbb{N}$ and $\tau$ is any topology that is compatible with the dual pair $(E, H)$ such that $(E, \tau)$ is an $L_{\varphi}(j)$-space $\left(L_{\rho}(j)\right.$-space $)$, then $(E, \tau(E, \overparen{H}))$ is an $L_{\varphi}(j+1)$-space ( $L_{\beta}(j+1)$-space).

Examples 3.3. (a) Each separable $F K(X)$-space, more generally each subWCG$F K(X)$-space, is an $L_{\varphi}$-space (see [8: Theorem 3.3]). Here, a subWCG-space is a (topological) subspace of a weakly compactly generated locally convex space.
(b) Every $S A K-K(X)$-space, in particular every $A K-K(X)$-space, is an $L_{\varphi}(1)$ space.
(c) The $B K(m)$-space $c(m)$ is an $L_{\varphi}(1)$-space, however, in general it is not separable and no $L_{\tau}$-space. (See [8: Example 3.13/(b)].)
(d) Based on an example of P. Erdös and G. Piranian [9] in [8: Example 3.12] a regular (real-valued) matrix $A$ is given such that the domain $c_{A}$ is an $L_{\beta}(1)$-space but no $L_{\varphi}(1)$-space. In Remark 4.2 below we will give an example of an $L_{\varphi}(2)$-space that is no $L_{\beta}(1)$-space. We do not know if the $L_{\beta}(2)$-spaces and the $L_{\varphi}(2)$-spaces coincide.

The following result will be needed in the next section. For sake of brevity we put $\stackrel{T}{S}^{0}=S$ (not to be confused with the polar of $\vec{S}$ ).

Proposition 3.4. Let $E$ and $F$ be locally convex spaces, $U<E^{*}, S<F^{*}$ and $i, j \in \mathbb{N}_{0}$. Let $T: E \longrightarrow F$ be a continuous linear mapping such that

$$
f \circ T \in \overparen{U}^{i} \quad \text { whenever } \quad f \in \widetilde{S}^{0}
$$

Then

$$
g \circ T \in \overleftarrow{U}^{i+j} \quad \text { whenever } \quad g \in \widetilde{S}^{j}
$$

Proof. We can assume $j>0$. Let $g \in \Gamma^{j}$. Then there are elements $f_{\nu_{i+1} \ldots \nu_{i+j}} \in S \cap F^{\prime \prime}$ for $\nu_{i+1}, \ldots, \nu_{i+j} \in \mathbb{N}$ such that:
(a) For $i+1 \leq \rho<i+j$ and all $\nu_{\rho+1}, \ldots, \nu_{i+j} \in \mathbb{N}$ the mappings

$$
y \longrightarrow \lim _{\nu_{p}} \ldots \lim _{\nu_{i+1}} f_{\nu_{i+1} \ldots \nu_{i+j}}(y) \quad(y \in F)
$$

exist and belong to $F^{\prime}$.
(b) For all $y \in F$ we have

$$
g(y)=\lim _{\nu_{i+j}} \ldots \lim _{\nu_{i+1}} f_{\nu_{i+1} \ldots \nu_{i+j}}(y)
$$

From our assumption we know that $f_{\nu_{i+1} \ldots \nu_{i+j}} \circ T \in \widetilde{U}^{\text {p }}$ for each $\nu_{i+1}, \ldots, \nu_{i_{i+j}} \in \mathbb{N}$. This implies that there are elements $g_{\nu_{1} \ldots \nu_{i} \nu_{i+1} \ldots \nu_{i+},} \in U \cap E^{\prime}$ for $\nu_{1}, \ldots, \nu_{i+j} \in \mathbb{N}$ such that:
(c) For $1 \leq \sigma<i$ and all $\nu_{a+1}, \ldots, \nu_{i}, \nu_{i+1}, \ldots, \nu_{i+j} \in \mathbb{I N}$ the mappings

$$
x \longrightarrow \lim _{\nu_{\sigma}} \ldots \lim _{\nu_{1}} g_{\nu_{1} \ldots \nu_{i} \nu_{i+1} \ldots \nu_{i+j}}(x) \quad(x \in E)
$$

exist and belong to $E^{\prime}$.
(d) For all $x \in E$ and $\nu_{i+1}, \ldots, \nu_{i+j} \in \mathbb{N}$ we have

$$
\left(f_{\nu_{i+1} \ldots \nu_{i+}} \circ T\right)(x)=\lim _{\nu_{i}} \ldots \lim _{\nu_{1}} g_{\nu_{1} \ldots \nu_{i} \nu_{i+1} \ldots \nu_{i+j}}(x)
$$

We thus have found elements $g_{\nu_{1} \ldots \nu_{i+j}} \in U \cap E^{\prime}$ for $\nu_{1}, \ldots, \nu_{i+j} \in \mathbb{N}$ with the following properties:
( $a^{\prime}$ ) For $1 \leq \rho<i+j$ and all $\nu_{\rho+1}, \ldots, \nu_{i+j} \in \mathbb{N}$ the mappings

$$
x \longrightarrow \lim _{\nu_{\rho}} \ldots \lim _{\nu_{1}} g_{\nu_{1} \ldots \nu_{i+j}}(x) \quad(x \in E)
$$

exist and belong to $E^{\prime}$ (this is just (c) in case $\rho<i$; for $\rho=i$ it follows from (d) and for $\rho>i$ from (a) if we note that $T$ is continuous).
(b') For all $x \in E$ we have

$$
(g \circ T)(x)=\lim _{\nu_{i+j}} \ldots \lim _{\nu_{1}} g_{\nu_{1} \ldots \nu_{i+j}}(x)
$$

(this follows from (b) and (d)).
But (a') and (b') together imply that $g \circ T \in \widetilde{U}^{i+j}$
Remark 3.5. Using the adjoint $T^{\prime}: F^{\prime} \longrightarrow E^{\prime}$ of the mapping $T$, the assertion of the proposition can be put more concisely as

$$
T^{\prime}\left({\vec{S}^{0}}^{0}\right) \subset \vec{U}^{i} \quad \text { implies } \quad T^{\prime}\left(\vec{S}^{j}\right) \subset \overleftarrow{U}^{i+j}
$$

## 4. Domains of operator-valued matrices

From [8: Theorems 3.9 and 3.10] it is known that the domain $c(Y)_{A}$ of an operator-valued matrix $A$ is an $L_{\beta}(1)$-space, and that $E_{A}$ is an $L_{\varphi}$-space whenever $E$ is an $L_{\beta}(1)$-space. Here we are going to improve these results.

Theorem 4.1. Let $E$ be a $K(Y)$-space, $A=\left(A_{n k}\right)$ a matrix with $A_{n k} \in B(X, Y)$ and let $j \in \mathbb{N}$.
(a) If $E$ is an $L_{\varphi}(j)-$ space, then $E_{A}$ is an $L_{\beta}(j)$-space.
(b) If $E$ is an $L_{\beta}(j)$-space, then $E_{A}$ is an $L_{\beta}(j+1)$-space.

Suppose that in addition $A$ is row-finite. Then:
(a') If $E$ is an $L_{\varphi}(j)$-space, then $E_{A}$ is an $L_{\varphi}(j)$-space.
(b') If $E$ is an $L_{\beta}(j)$-space, then $E_{A}$ is an $L_{\varphi}(j+1)$-space.
Special case (see [8: Theorem 3.9]): $c(Y)_{A}$ is an $L_{\beta}(1)$-space, and even an $L_{\varphi}(1)-$ space if $A$ is row-finite.

Remark 4.2. Example 3.3/(d) tells us that, in general, we cannot replace ' $L_{\beta}(j)-$ space' by ' $L_{\varphi}(j)$-space' in statement (a). Assertion (a') is obviously best-possible, while in statement (b') we cannot replace ' $L_{\varphi}(j+1)$-space' by ' $L_{\beta}(j)$-space' in general: In [8: Example 3.14] there is an example of a (real-valued) row-finite matrix $A$ and an $L_{\beta}(1)$ space $E$ such that the domain $E_{A}$ is no $L_{\beta}(1)$-space. (From statement (b') above we see that it is an $L_{\varphi}(2)$-space.) We do not know if one can replace ' $L_{\beta}(j+1)$-space' in statement (b) by ' $L_{\varphi}(j+1)$-space'.

Proof of Theorem 4.1. Let $E$ be a $K(Y)$-space, and let $f \in E_{A}^{\prime}$ be given. Then we may choose elements $g \in E^{\prime}$ and $h \in \omega(Y)_{A}^{\beta}=\omega(Y)_{A}^{\prime}$ with $f=g \circ A+h$ (see [1:
( Proposition 2.10] and [5: Theorem 2.14/(b)]). Since $E_{A} \subset \omega(Y)_{A}$, we have $h \in E_{A}^{\beta} \subset$ $\varphi\left(X^{\prime}\right) \subset \widetilde{E}_{A}^{\beta}$ for all $j \in \mathbb{N}$. Hence in order to prove the various statements of the theorem we need only show that $g \circ A$ belongs to ${\bar{E}_{A}^{\beta}}^{j},{\bar{E}_{A}^{\beta}}^{j+1},{\widetilde{\varphi}\left(X^{\prime}\right)}^{j}$ and ${\bar{\varphi}_{\varphi\left(X^{\prime}\right)}}^{j+1}$, respectively. To this end we apply Proposition 3.4 to the mapping $A: E_{A} \longrightarrow E$.
(a) Let $E$ be an $L_{\varphi}(j)$-space. Then $g \in E^{\prime} \subset{\overleftarrow{\varphi\left(Y^{\prime}\right)}}^{j}$. Here we choose $U=E_{A}^{\beta}$, $S=\varphi\left(Y^{\prime}\right)$ and $i=0$. If $\Phi=\left(\Phi_{n}\right)_{n=1}^{N} \in \varphi\left(Y^{\prime}\right)$, then we have for $x \in E_{A}$

$$
(\Phi \circ A)(x)=\sum_{n=1}^{N} \Phi_{n}\left(\sum_{k=1}^{\infty} A_{n k}\left(x_{k}\right)\right)=\sum_{k=1}^{\infty}\left(\sum_{n=1}^{N} \Phi_{n} \circ A_{n k}\right)\left(x_{k}\right)
$$

so that $\Phi \circ A \in E_{A}^{\beta}$. Hence the hypothesis of Proposition 3.4 holds, so that $g \circ A \in \stackrel{E_{A}^{\beta}}{ }$, as desired.
(b) Let $E$ be an $L_{\beta}(j)$-space. Then $g \in E^{\prime} \subset{\widetilde{E^{\beta}}}^{j}$. Here we choose $U=E_{A}^{\beta}$, $S=E^{\beta}$ and $i=1$. If $\Phi=\left(\Phi_{n}\right) \in E^{\beta}$, then we have for $x \in E_{A}$

$$
(\Phi \circ A)(x)=\lim _{m \rightarrow \infty} \sum_{n=1}^{m} \Phi_{n}\left(\sum_{k=1}^{\infty} \mathscr{A _ { n k }}\left(x_{k}\right)\right)=\lim _{m \rightarrow \infty} \sum_{k=1}^{\infty}\left(\sum_{n=1}^{m} \Phi_{n} \circ A_{n k}\right)\left(x_{k}\right)
$$

so that $\Phi \circ A \in{E_{A}^{\beta}}^{1}$. Proposition 3.4 implies that $g \circ A \in{E_{A}^{\beta}}^{+1}$.
Now suppose that $A$ is row-finite.
(a') Let $E$ be an $L_{\varphi}(j)$-space. Then $g \in E^{\prime} \subset{\widetilde{\varphi}\left(Y^{\prime}\right)}^{j}$. Here we choose $U=\varphi\left(X^{\prime}\right)$, $S=\varphi\left(Y^{\prime}\right)$ and $i=0$. If $\Phi=\left(\Phi_{n}\right)_{n=1}^{N} \in \varphi\left(Y^{\prime}\right)$, then we have for $x \in E_{A}$

$$
(\Phi \circ A)(x)=\sum_{k=1}^{\infty}\left(\sum_{n=1}^{N} \Phi_{n} \circ A_{n k}\right)\left(x_{k}\right)
$$

and hence $\Phi \circ A \in \varphi\left(X^{\prime}\right)$. Now Proposition 3.4 implies that $g \circ A \in{\overline{\varphi\left(X^{\prime}\right)}}^{i}$.
(b') This follows from statement (a') since every $L_{\beta}(j)$-space is also an $L_{\varphi}(j+1)-$ space

## 5. Matrix maps into $L_{\varphi}-K-$ spaces

The aim of this section is to show that the class of $L_{\varphi}$-spaces is the complete analogue of Qiu's $L_{r}$-spaces if closed linear mappings are replaced by matrix mappings. We also prove that the matrix domain $E_{A}$ of an operator-valued matrix is an $L_{\varphi}$-space whenever $E$ is an $L_{\varphi}$-space. This result may be considered as a generalization of the classical fact that the matrix domain $E_{A}$ of a scalar-valued matrix is separable if $E$ is a separable FK-space.

Our first result is the analogue for matrix mappings of Qiu's extension of Kalton's closed graph theorem. It generalizes the results in Theorem 4.2 and Theorem 4.4./(a) $\Rightarrow$ (b) of [8].

Theorem 5.1. Let $E$ be a $K(X)$-space and $F$ a $K(Y)$-space. If $E$ is a Mackey space, ( $E^{\prime}, \sigma\left(E^{\prime}, E\right)$ ) is sequentially complete and $F$ is an $L_{\varphi}$-space, then every (weak) matrix mapping $A: E \longrightarrow F$ is continuous.

Proof. We put

$$
D_{A}^{*}:=\left(A^{\prime}\right)^{-1}\left(E^{\prime}\right)=\left\{f \in F^{*} \mid f \circ A \in E^{\prime}\right\}
$$

and $D_{A}:=D_{A}^{*} \cap F^{\prime}$. If we can show that $D_{A}=F^{\prime}$, then $A$ is weakly continuous hence continuous as $E$ is a Mackey space.

To that end let $f \in F^{*}$ and $\left(f_{n}\right)$ in $F^{*}$ with $f_{n} \circ A \in E^{\prime}$ and $f_{n} \longrightarrow f$ in $\left(F^{*}, \sigma\left(F^{*}, F\right)\right)$ be given. Then we have $f_{n} \circ A, \longrightarrow f \circ A$ in $\left(E^{*}, \sigma\left(E^{*}, E\right)\right)$. Since ( $E^{\prime}, \sigma\left(E^{\prime}, E\right)$ ) is sequentially complete, this shows that $f \circ A \in E^{\prime}$, so that $f \in D_{A}^{*}$. Thus $D_{A}^{*}$ is $\sigma\left(F^{*}, F\right)$-sequentially closed, which implies that $D_{A} \subset D_{A}^{*}$, hence $D_{A} \cap F^{\prime}=D_{A}$.

We next show that $\varphi\left(Y^{\prime}\right) \subset D_{A}$. For this it suffices to prove that for each $g \in Y^{\prime}$ and $n \in \mathbb{N}$ the mapping $x \longrightarrow g\left(\sum_{k=1}^{\infty} A_{n k}\left(x_{k}\right)\right)$ belongs to $E^{\prime}$. But since we have

$$
g\left(\sum_{k=1}^{\infty} A_{n k}\left(x_{k}\right)\right)=\lim _{m} \sum_{k=1}^{m}\left(g \circ A_{n k}\right)\left(x_{k}\right)
$$

for all $x \in E$, this follows from the weak sequential completeness of $E^{\prime}$.

In conclusion, $\widehat{D_{A}} \cap F^{\prime}=D_{A}, \varphi\left(Y^{\prime}\right) \subset D_{A}$ and the fact that $F$ is an $L_{\varphi}$-space imply that

$$
\dot{F^{\prime}}=\stackrel{\varphi\left(Y^{\prime}\right)}{\square} F^{\prime} \subset \overline{D_{A}} \cap F^{\prime}=D_{A}
$$

which had to be shown
Remark 5.2. The proof shows that the theorem remains true for any linear mapping $A=\left(A_{n}\right): E \longrightarrow F$ with the property that $\varphi\left(Y^{\prime}\right) \subset D_{A}$, which is equivalent to the continuity of each mapping $A_{n}: E \longrightarrow Y(n \in \mathbb{N})$.

The next result is the analogue to Qiu's characterization of $L_{r}$-spaces [11]. It shows that the class of $L_{\varphi}$-spaces is the maximal class of range spaces in Theorem 5.1.

Theorem 5.3. Let $F$ be a $K(X)$-space. Then the following statements are equivalent:
(a) $F$ is an $L_{\varphi}$-space.
(b) For each $K(X)$-space $E$ that is a Mackey space such that $\left(E^{\prime}, \sigma\left(E^{\prime}, E\right)\right)$ is sequentially complete every matrix mapping $A: E \longrightarrow F$ is continuous.

Proof. The implication (a) $\Rightarrow(\mathrm{b})$ is contained in Theorem 5.1. The converse implication follows immediately from the following remark

Remark 5.4. Let $F$ be a $K(X)$-space. If the inclusion map

$$
i:\left(F, \tau\left(F, F^{\beta}\right)\right) \rightarrow F
$$

is continuous, then $F$ is an $L_{\varphi}$-space. (Namely, in this situation we have $F^{\prime} \subset \overrightarrow{F^{\beta}}=$ $\stackrel{\llcorner }{\varphi\left(X^{\prime}\right)}$.).

Using the last remark we can now obtain a permanence result for $L_{\varphi}$-spaces under the formation of matrix domains, answering a question in [8].

Theorem 5.5. Let $A=\left(A_{n k}\right)$ be a matrix with $A_{n k} \in B(X, Y)$. If $E$ is an $L_{\varphi}-$ $K(Y)$-space, then $E_{A}$ is an $L_{\varphi}-K(X)$-space.

Proof. By Remark 5.4 we have to prove the continuity of

$$
i:\left(E_{A}, \tau\left(E_{A}, \overline{E_{A}^{\beta}}\right)\right) \longrightarrow E_{A}
$$

which is equivalent to the continuity of the inclusion map

$$
i_{\omega}:\left(E_{A}, \tau\left(E_{A}, \overline{E_{A}^{\beta}}\right)\right) \longrightarrow \omega(Y)_{A}
$$

and of the map

$$
A:\left(E_{A}, \tau\left(E_{A}, \stackrel{E_{A}^{\beta}}{ }\right)\right) \longrightarrow E, x \longrightarrow A x
$$

However, since in both cases the range space is an $L_{\varphi}$-space (note that $\omega(Y)_{A}$ is an $A K$-space by [5: Theorem 2.14]), this is an immediate corollary of Theorem 5.1

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