

## The Structure of Local Solutions of Partial Differential Equations of the Fuchsian Type

by

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Linear partial differential equations with regular singularity along a hypersurface were studied by several authors, say, Hasegawa [10][11], Baouendi-Goulaouic [3][4], Alinhac [1][2], Froim [7][8][9], Delache-Leray [6], Kashiwara-Oshima [13], Tsuno [15], etc... in various problems. In this note, we consider the hyperfunction solutions of certain type equations with regular singularity. The details of this note will be published in [14] anywhere else.

Let  $(t, z) \in \mathbf{C} \times \mathbf{C}^n$  and let

$$P(t, z, D_t, D_z) = t^k D_t^m + P_1(t, z, D_z) t^{k-1} D_t^{m-1} + \dots \\ + P_k(t, z, D_z) D_t^{m-k} + \dots + P_m(t, z, D_z)$$

be a linear differential operator whose coefficients are holomorphic functions defined in a neighbourhood of the origin such that

$$(A-i) \quad 0 \leq k \leq m$$

$$(A-ii) \quad \text{order of } P_j(t, z, D_z) \leq j \text{ for } 1 \leq j \leq m$$

$$(A-iii) \quad \text{order of } P_j(0, z, D_z) \leq 0 \text{ for } 1 \leq j \leq k.$$

Then  $P$  is said of the Fuchsian type with weight  $m-k$  with respect to  $t$  (by [3]). By the condition (A-iii),  $P_j(0, z, D_z)$  is a function. We set  $P_j(0, z, D_z) = a_j(z)$  for  $1 \leq j \leq k$ . Then the indicial equation associated with  $P$  is defined by

$$\mathcal{E}(\lambda, z) = \lambda(\lambda-1) \cdots (\lambda-m+1) + a_1(z) \lambda(\lambda-1) \cdots (\lambda-m+2)$$

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$$+ \dots + a_k(z)\lambda(\lambda-1)\dots(\lambda-m+k+1).$$

The roots, that we call the characteristic exponents of  $P$ , are denoted by  $\lambda=0, 1, \dots, m-k-1, \rho_1(z), \dots, \rho_k(z)$ . They are functions of  $z$ .

We set

$\tilde{\mathcal{O}}$  = the set of all the germs of multivalued holomorphic functions on  $\mathbf{C} \times \mathbf{C}^n \setminus \{t=0\}$  at the origin.

Then we have the next theorem.

**Theorem 1.** *Assume that  $\rho_i(0), \rho_i(0) - \rho_j(0) \notin \mathbf{Z}$  holds for  $1 \leq i \neq j \leq k$ . Then the equation  $Pu=f$  is always solvable in  $\tilde{\mathcal{O}}$ . Moreover there exist holomorphic functions  $K_i(t, z, w)$  ( $0 \leq i \leq m-k-1$ ),  $L_j(t, z, w)$  ( $1 \leq j \leq k$ ) on*

$$U_\varepsilon = \{(t, z, w) \in \mathbf{C} \times \mathbf{C}^n \times \mathbf{C}^n; |t|, |z|, |w| < \varepsilon, \\ |t| < M|z_i - w_i|^s, i=1, \dots, n\}$$

$$s = \min(m, k+1), M = \text{constant}$$

which satisfy the following conditions:

(1) For any holomorphic functions  $\varphi_i(w), \psi_j(w)$  at the origin, we set

$$u(t, z) = \sum_{i=0}^{m-k-1} \oint K_i(t, z, w) t^i \varphi_i(w) dw \\ + \sum_{j=1}^k \oint L_j(t, z, w) t^{\rho_j(w)} \psi_j(w) dw$$

Then  $u(t, z)$  is a solution of the equation  $Pu=0$  in  $\tilde{\mathcal{O}}$ .

(2) If  $u(t, z) \in \tilde{\mathcal{O}}$  and  $Pu=0$  holds, then  $u(t, z)$  is uniquely expressed in the form (1).

Next, we consider the equation in the real domain and investigate the structure of hyperfunction solutions. Let  $(t, x) \in \mathbf{R} \times \mathbf{R}^n$  and let  $P(t, x, D_t, D_x)$  be of the Fuchsian type with weight  $m-k$  with respect to  $t$ . Moreover we assume the following conditions on  $P$ :

(A-iv)  $\sigma_m(P)$  has the form:  $\sigma_m(P)(t, x, \tau, \xi) = t^k p_m(t, x, \tau, \xi)$

(A-v) All the roots  $\tau(t, x, \xi)$  of the equation  $p_m(t, x, \tau, \xi) = 0$  are real, when  $t, x, \xi$  are real (near the origin).

Then we say that  $P$  is a *Fuchsian hyperbolic operator with respect to  $t$* . Note that if  $k=0$ , then  $P$  is nothing but a weakly hyperbolic operator in the direction  $dt$  ([5]).

Under these assumptions, we can give the meaning as hyperfunctions to the above  $K_i(t, z, w)$ ,  $L_j(t, z, w)$  in Theorem 1. We also denote these hyperfunctions by  $K_i(t, x, y)$ ,  $L_j(t, x, y)$  respectively. then  $K_i, L_j$  satisfy the following conditions:

$$\begin{aligned} \text{Supp } K_i, L_j &\subset \{(t, x, y); |x-y| \leq M|t|^{1/s}\} \\ S\text{-}S(K_i), (L_j) &\subset \{(t, x, y, \sqrt{-1}(\tau, \xi, \eta) \infty); |x-y| \leq M|t|^{1/s}, \\ &|\tau| \leq M|\xi|, |\xi + \eta| \leq M|\xi||t|^{1/s}\}. \end{aligned}$$

Using these hyperfunctions, we have the next theorem.

**Theorem 2.** *Assume that  $\rho_i(0), \rho_i(0) - \rho_j(0) \notin \mathbb{Z}$  holds for  $1 \leq i \neq j \leq k$ . Then the equation  $Pu=f$  is always solvable in  $\mathcal{B}$  (where  $\mathcal{B}$  is the stalk of the sheaf of hyperfunctions at the origin). Moreover the above  $K_i(t, x, y)$  ( $0 \leq i \leq m-k-1$ ),  $L_j(t, x, y)$  ( $1 \leq j \leq k$ ) satisfy the following conditions:*

(1) *For any hyperfunctions  $\varphi_i(y), \psi_j^\pm(y)$  at the origin, we set*

$$\begin{aligned} u(t, x) &= \sum_{i=0}^{m-k-1} \int K_i(t, x, y) t^i \varphi_i(y) dy \\ &\quad + \sum_{j=1}^k \sum_{\pm} \int L_j(t, x, y) (t \pm i0)^{\rho_j(y)} \psi_j^\pm(y) dy \end{aligned}$$

or

$$\begin{aligned} u(t, x) &= \sum_{i=0}^{m-k-1} \int K_i(t, x, y) t^i \varphi_i(y) dy \\ &\quad + \sum_{j=1}^k \sum_{\pm} \int L_j(t, x, y) t_{\pm}^{\rho_j(y)} \psi_j^\pm(y) dy \end{aligned}$$

Then  $u(t, x)$  is a solution of the equation  $Pu=0$  in  $\mathcal{B}$ .

(2) *If  $u(t, x) \in \mathcal{B}$  and  $Pu=0$  holds, then  $u(t, x)$  is uniquely expressed in the form (1).*

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