

The Structure of Local Solutions of Partial Differential Equations of the Fuchsian Type

by

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Linear partial differential equations with regular singularity along a hypersurface were studied by several authors, say, Hasegawa [10][11], Baouendi-Goulaouic [3][4], Alinhac [1][2], Froim [7][8][9], Delache-Leray [6], Kashiwara-Oshima [13], Tsuno [15], etc... in various problems. In this note, we consider the hyperfunction solutions of certain type equations with regular singularity. The details of this note will be published in [14] anywhere else.

Let $(t, z) \in \mathbf{C} \times \mathbf{C}^n$ and let

$$P(t, z, D_t, D_z) = t^k D_t^m + P_1(t, z, D_z) t^{k-1} D_t^{m-1} + \dots \\ + P_k(t, z, D_z) D_t^{m-k} + \dots + P_m(t, z, D_z)$$

be a linear differential operator whose coefficients are holomorphic functions defined in a neighbourhood of the origin such that

$$(A-i) \quad 0 \leq k \leq m$$

$$(A-ii) \quad \text{order of } P_j(t, z, D_z) \leq j \text{ for } 1 \leq j \leq m$$

$$(A-iii) \quad \text{order of } P_j(0, z, D_z) \leq 0 \text{ for } 1 \leq j \leq k.$$

Then P is said of the Fuchsian type with weight $m-k$ with respect to t (by [3]). By the condition (A-iii), $P_j(0, z, D_z)$ is a function. We set $P_j(0, z, D_z) = a_j(z)$ for $1 \leq j \leq k$. Then the indicial equation associated with P is defined by

$$\mathcal{E}(\lambda, z) = \lambda(\lambda-1) \cdots (\lambda-m+1) + a_1(z) \lambda(\lambda-1) \cdots (\lambda-m+2)$$

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$$+ \dots + a_k(z)\lambda(\lambda-1)\dots(\lambda-m+k+1).$$

The roots, that we call the characteristic exponents of P , are denoted by $\lambda=0, 1, \dots, m-k-1, \rho_1(z), \dots, \rho_k(z)$. They are functions of z .

We set

$\tilde{\mathcal{O}}$ = the set of all the germs of multivalued holomorphic functions on $\mathbf{C} \times \mathbf{C}^n \setminus \{t=0\}$ at the origin.

Then we have the next theorem.

Theorem 1. *Assume that $\rho_i(0), \rho_i(0) - \rho_j(0) \notin \mathbf{Z}$ holds for $1 \leq i \neq j \leq k$. Then the equation $Pu=f$ is always solvable in $\tilde{\mathcal{O}}$. Moreover there exist holomorphic functions $K_i(t, z, w)$ ($0 \leq i \leq m-k-1$), $L_j(t, z, w)$ ($1 \leq j \leq k$) on*

$$U_\varepsilon = \{(t, z, w) \in \mathbf{C} \times \mathbf{C}^n \times \mathbf{C}^n; |t|, |z|, |w| < \varepsilon, \\ |t| < M|z_i - w_i|^s, i=1, \dots, n\}$$

$$s = \min(m, k+1), M = \text{constant}$$

which satisfy the following conditions:

(1) For any holomorphic functions $\varphi_i(w), \psi_j(w)$ at the origin, we set

$$u(t, z) = \sum_{i=0}^{m-k-1} \oint K_i(t, z, w) t^i \varphi_i(w) dw \\ + \sum_{j=1}^k \oint L_j(t, z, w) t^{\rho_j(w)} \psi_j(w) dw$$

Then $u(t, z)$ is a solution of the equation $Pu=0$ in $\tilde{\mathcal{O}}$.

(2) If $u(t, z) \in \tilde{\mathcal{O}}$ and $Pu=0$ holds, then $u(t, z)$ is uniquely expressed in the form (1).

Next, we consider the equation in the real domain and investigate the structure of hyperfunction solutions. Let $(t, x) \in \mathbf{R} \times \mathbf{R}^n$ and let $P(t, x, D_t, D_x)$ be of the Fuchsian type with weight $m-k$ with respect to t . Moreover we assume the following conditions on P :

(A-iv) $\sigma_m(P)$ has the form: $\sigma_m(P)(t, x, \tau, \xi) = t^k p_m(t, x, \tau, \xi)$

(A-v) All the roots $\tau(t, x, \xi)$ of the equation $p_m(t, x, \tau, \xi) = 0$ are real, when t, x, ξ are real (near the origin).

Then we say that P is a *Fuchsian hyperbolic operator with respect to t* . Note that if $k=0$, then P is nothing but a weakly hyperbolic operator in the direction dt ([5]).

Under these assumptions, we can give the meaning as hyperfunctions to the above $K_i(t, z, w)$, $L_j(t, z, w)$ in Theorem 1. We also denote these hyperfunctions by $K_i(t, x, y)$, $L_j(t, x, y)$ respectively. then K_i, L_j satisfy the following conditions:

$$\begin{aligned} \text{Supp } K_i, L_j &\subset \{(t, x, y); |x-y| \leq M|t|^{1/s}\} \\ S\text{-}S(K_i), (L_j) &\subset \{(t, x, y, \sqrt{-1}(\tau, \xi, \eta) \infty); |x-y| \leq M|t|^{1/s}, \\ &|\tau| \leq M|\xi|, |\xi + \eta| \leq M|\xi||t|^{1/s}\}. \end{aligned}$$

Using these hyperfunctions, we have the next theorem.

Theorem 2. *Assume that $\rho_i(0), \rho_i(0) - \rho_j(0) \notin \mathbb{Z}$ holds for $1 \leq i \neq j \leq k$. Then the equation $Pu=f$ is always solvable in \mathcal{B} (where \mathcal{B} is the stalk of the sheaf of hyperfunctions at the origin). Moreover the above $K_i(t, x, y)$ ($0 \leq i \leq m-k-1$), $L_j(t, x, y)$ ($1 \leq j \leq k$) satisfy the following conditions:*

(1) *For any hyperfunctions $\varphi_i(y), \psi_j^\pm(y)$ at the origin, we set*

$$\begin{aligned} u(t, x) &= \sum_{i=0}^{m-k-1} \int K_i(t, x, y) t^i \varphi_i(y) dy \\ &\quad + \sum_{j=1}^k \sum_{\pm} \int L_j(t, x, y) (t \pm i0)^{\rho_j(y)} \psi_j^\pm(y) dy \end{aligned}$$

or

$$\begin{aligned} u(t, x) &= \sum_{i=0}^{m-k-1} \int K_i(t, x, y) t^i \varphi_i(y) dy \\ &\quad + \sum_{j=1}^k \sum_{\pm} \int L_j(t, x, y) t_{\pm}^{\rho_j(y)} \psi_j^\pm(y) dy \end{aligned}$$

Then $u(t, x)$ is a solution of the equation $Pu=0$ in \mathcal{B} .

(2) *If $u(t, x) \in \mathcal{B}$ and $Pu=0$ holds, then $u(t, x)$ is uniquely expressed in the form (1).*

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