Uniqueness Theorems
in Linear Theory of Microporous Solids

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Abstract. This paper deals with uniqueness theorems for external boundary value problems
and a contact problem for a system of differential equations of the linear elasticity theory of
microporous solids. Here we have derived an asymptotic representation of the solution of this
system in a neighbourhood of infinity which has enabled us to prove new uniqueness theorems.

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theorems

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1. Differential equations

The system of differential equations of the linear elasticity theory of microporous solids
is written in the following form (see [1, 3, 6, 7]):

\[ \mu \Delta u + (\lambda + \mu + \eta) \text{grad div } u - \eta \text{grad } \theta = -\varphi f \]  
\[ \chi \Delta \theta - \delta \theta + \eta \text{div } u = 0 \]

where \( u = (u_1, u_2, u_3) \) is the displacement vector, \( \theta \) is the dilatation, \( \lambda, \mu \) are the Lamé
modules of the solid part of the microporous material, \( \varrho \) is the density, and \( \eta, \delta, \chi \) are
further material constants, whose physical properties are discussed in [3, 6, 7].

The fundamental equations (1),(2) we can write in the following matrix form:

\[ B(\partial_x) U(x)^T + F(x)^T = 0, \]

where

\[ U = (u_1, u_2, u_3, \theta), \quad F = (\varphi f_1, \varphi f_2, \varphi f_3, 0) \]

\[ U_i = u_i \quad (i = 1, 2, 3) \quad \text{and} \quad U_4 = \theta, \quad F_i = \varphi f_i \quad (i = 1, 2, 3) \quad \text{and} \quad F_4 = 0 \]
$B(\partial_x) = \|B_{ik}(\partial_x)\|_{4 \times 4}$

$B_{ik}(\partial_x) = \delta_{ik}\mu \Delta + \gamma \frac{\partial^2}{\partial x_i \partial x_k} (i, k = 1, 2, 3)$ and $B_{4k}(\partial_x) = -\eta \frac{\partial}{\partial x_i} (i = 1, 2, 3)$

$B_{4k}(\partial_x) = \eta \frac{\partial}{\partial x_k} (k = 1, 2, 3)$ and $B_{44}(\partial_x) = \chi \Delta - \delta,$

$\gamma = \lambda + \mu + \eta$, $\delta_{ik}$ is the Kronecker symbol. It is assumed that the material constants $\lambda, \mu, \delta, \eta, \chi$ satisfy the conditions (see [6, 7])

$$\mu, \delta, \chi, (\lambda + \frac{2\mu}{3} + \eta)\delta - \eta^2 > 0.$$  

(4)

The derivation of asymptotic representations mainly rests on the behaviour of the fundamental solution of the considered system.

2. Fundamental solution

The fundamental solution of equations (3) can be written in the following form (see [1, 3, 6, 7]; $i, k = 1, 2, 3$):

$$\Gamma(x) = \|\Gamma_{ik}\|_{4 \times 4}$$

$$\Gamma_{ik}(x) = \frac{-1}{4\pi \mu} \left( \frac{\delta_{ik}}{|x|} - \frac{q_2}{2q_1 \partial x_i \partial x_k} + \frac{\mu \eta^2}{q_1^2} \frac{\partial^2}{\partial x_i \partial x_k} \frac{1 - e^{-|x|}}{|x|} \right)$$

$$\Gamma_{4i}(x) = \frac{1}{4\pi q_1} \frac{\eta \partial}{\partial x_i} \frac{1 - e^{-|x|}}{|x|}$$

$$\Gamma_{44}(x) = -\frac{e^{-|x|}}{4\pi \chi |x|}$$

$$q_1 = (\lambda + 2\mu + \eta)\delta - \eta^2, \quad q_2 = (\lambda + \mu + \eta)\delta - \eta^2$$

$$m^2 = (\lambda + 2\mu + \eta)\frac{\chi}{q_1}.$$ 

(5)

By virtue of the inequalities (4) we have

$$\lambda + 2\mu + \eta > \frac{\eta^2}{\delta} + \frac{4}{3} \mu > 0, \quad m^2 > 0,$$

$$q_1 = \frac{4}{3} \mu \delta + (\lambda + \frac{2}{3}\mu + \eta)\delta - \eta^2 \geq \frac{4}{3} \mu \delta > 0.$$ 

Let us establish the properties of the fundamental matrix $\Gamma = \|\Gamma_{ik}\|_{4 \times 4}$ in a neighbourhood of infinity. In (5) it was used that

$$m = +\sqrt{(\lambda + 2\mu + \eta)\frac{\chi}{q_1}}.$$  

(6)

By virtue of (5) and (6) we have the following estimates:

$$|\partial^o \Gamma_{ik}(x)| \leq C|x|^{-1-l_{\|0}} (i, k = 1, 2, 3)$$

$$|\partial^o \Gamma_{4i}(x)| \leq C|x|^{-2-l_{\|0}} (i = 1, 2, 3)$$

$$|\partial^o \Gamma_{44}(x)| \leq C|x|^{-2-l_{\|0}} (k = 1, 2, 3)$$

$$|\partial^o \Gamma_{44}(x)| \leq C|x|^{-n}$$

(7)
for some positive number C. Here \( \alpha = (\alpha_1, \alpha_2, \alpha_3) \) is an arbitrary multiindex, \( n \) is an arbitrary non-negative integer.

The derivation of the asymptotic representation formula for the solution of the system (3) in a neighbourhood of infinity [2] is based on the Green and Somigliana formulas [1].

3. Integral theorems

Let \( \Omega \) be a bounded domain in \( \mathbb{R}^3 \) with a piecewise smooth boundary \( \partial \Omega, U = (U_1, U_2, U_3, U_4) \in C^1(\Omega) \cap C^2(\Omega), V = (V_1, V_2, V_3, V_4) \in C^1(\Omega) \cap C^2(\Omega), \nu = (\nu_1, \nu_2, \nu_3) \) the unit normal to \( \partial \Omega \) at the point \( y \), external with respect to \( \Omega \). Then we obtain

\[
\int_{\partial \Omega} \left( V_i(z) B_{ik}(\partial_z) U_k(z) + 2W(U,V)(z) \right) \, dz = \int_{\partial \Omega} V_i(y) R_{ik}(\partial_y, \nu) U_k(y) \, d_v S, \tag{8}
\]

where \( W(U,V) \) is a bilinear form:

\[
W(U,V) = \frac{1}{2}(\lambda + \mu) \sum_{i,j=1}^{3} \frac{\partial U_i}{\partial x_i} \frac{\partial V_j}{\partial x_j} + \frac{\mu}{4} \sum_{i,j=1}^{3} \left( \frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \left( \frac{\partial V_i}{\partial x_j} + \frac{\partial V_j}{\partial x_i} \right) - \frac{1}{2} \eta U_4 \sum_{i=1}^{3} \frac{\partial U_i}{\partial x_i} - \frac{1}{2} \eta V_4 \sum_{i=1}^{3} \frac{\partial U_i}{\partial x_i} + \frac{1}{2} \delta U_4 V_4 + \frac{1}{2} \chi \sum_{i=1}^{3} \frac{\partial U_i}{\partial x_i} \frac{\partial V_4}{\partial x_i}
\]

\[
R(\partial_y, \nu) = \| R_{ik}(\partial_y, \nu) \|_{4 \times 4} \tag{9}
\]

\[
R_{ik}(\partial_y, \nu) = \delta_{ik} \mu \sum_{j=1}^{3} \nu_j \frac{\partial}{\partial y_j} + (\lambda + \eta) \nu_i \frac{\partial}{\partial y_k} + \mu \nu_k \frac{\partial}{\partial y_i} \quad (i, k = 1, 2, 3)
\]

\[
R_{44}(\partial_y, \nu) = -\eta \nu_i, \quad R_{44}(\partial_y, \nu) = 0 \quad (i = 1, 2, 3)
\]

In the sequel (as in formula (8)) the summation sign \( \sum \) will frequently be omitted and the index repetition in the monomial will imply summation from 1 to 4.

Because of the symmetry \( W(U,V) = W(V,U) \), Green's second identity follows from equality (8):

\[
\int_{\partial \Omega} \left( V_i(z) B_{ik}(\partial_z) U_k(z) - U_k(z) B_{ki}(\partial_z) V_i(z) \right) \, dz = \int_{\partial \Omega} \left( V_i(y) R_{ik}(\partial_y, \nu) U_k(y) - U_k(y) R_{ki}(\partial_y, \nu) V_i(y) \right) \, d_v S. \tag{10}
\]

Here summation is taken over the index \( i \) and \( k \) from 1 to 4.
Let \( U \in C^1(\Omega) \cap C^2(\Omega) \) and, for all \( x \in \Omega \), \( B(\partial_x)U(x) = 0 \). Then the Somigliana formula is valid \([1]\), i.e. for all \( x \in \Omega \) we have \((j = 1, 2, 3, 4)\)

\[
U_j(x) = \int_{\partial \Omega} \left( U_i(y)R_{ik}(\partial_y, \nu)\Gamma_{kj}(y - x) - \Gamma_{kj}(y - x)R_{ki}(\partial_y, \nu)U_i(y) \right) d\nu S.
\]

4. Formulation of the problems

We consider the following boundary value problems and a general contact problem for the system of differential equations of the elasticity theory of microporous solids. Let \( \Omega^+ \) be a bounded domain in \( \mathbb{R}^3 \),

\[
\Omega^- = \mathbb{R}^3 \setminus \overline{\Omega^+}, \quad S = \partial \Omega^+ = \partial \Omega^-.
\]

Find in \( \Omega^\pm \) a solution \( U \) of system (3) with one of the boundary conditions below:

- Problems \((1,1)^\pm\): For all \( y \in S \) let
  \[
  U^+(y) = \lim_{\Omega^- \ni x \ni y \in S} U(x) = \psi(y), \quad U^-(y) = \lim_{\Omega^+ \ni x \ni y \in S} U(x) = \psi(y).
  \]

- Problems \((1,2)^\pm\): For all \( y \in S \) let
  \[
  U_i^\pm(y) = \psi_i(y) \quad (i = 1, 2, 3), \quad \chi \left( \frac{\partial U_i}{\partial \nu} \right)^\pm(y) = \psi_4(y).
  \]

- Problems \((2,1)^\pm\): For all \( y \in S \) let
  \[
  (R_{ik}(\partial_y, \nu)U_k)^\pm(y) = \varphi_i(y) \quad (i = 1, 2, 3), \quad U_4^\pm(y) = \varphi_4(y).
  \]

- Problems \((2,2)^\pm\): For all \( y \in S \) let
  \[
  (R(\partial_y, \nu)U)^\pm(y) = \varphi(y).
  \]

Here \( \psi = (\psi_1, \psi_2, \psi_3, \psi_4) \) and \( \varphi = (\varphi_1, \varphi_2, \varphi_3, \varphi_4) \) are given functions on \( S \). It will be assumed below that a microporous medium, with the material constants \( \lambda^+, \mu^+, \eta^+, \delta^+, \chi^+ \), occupies domain \( \Omega^+ \) and a microporous medium with the material constants \( \lambda^-, \mu^-, \eta^-, \delta^-, \chi^- \) occupies domain \( \Omega^- \). Now let us formulate the general contact problem.

- Problem (3): Find in \( \Omega^+ \) and in \( \Omega^- \) a solution \( U \) of the system

  \[
  B^+(\partial_x)U(x) = 0 \quad \text{for all } x \in \Omega^+, \quad B^-(\partial_x)U(x) = 0 \quad \text{for all } x \in \Omega^-
  \]

  with the transmission conditions for all \( y \in S \)

  \[
  U^+(y) - U^-(y) = \psi(y), \quad (R^+(\partial_y, \nu)U)^+(y) - (R^-(\partial_y, \nu)U)^-(y) = \varphi(y).
  \]

Here \( B^+, R^+ \) are the operators \( B, R \) formed with the material constants \( \lambda^+, \mu^+, \eta^+, \delta^+, \chi^+ \) and \( B^-, R^- \) are the operators \( B, R \) with the material constants \( \lambda^-, \mu^-, \eta^-, \delta^-, \chi^- \).
5. Uniqueness theorem

A vector \( U = (U_1, U_2, U_3, U_4) \), defined in \( \Omega^+ \), we call regular in \( \Omega^+ \) if \( U \in C^2(\Omega^+) \cap C^1(\overline{\Omega^+}) \). A vector \( U \), defined in \( \Omega^- \), we call regular in \( \Omega^- \) if \( U \in C^2(\Omega^-) \cap C^1(\overline{\Omega^-}) \) and if it admits in a neighbourhood of infinity the estimates

\[
U(x) = O\left(\frac{1}{|x|}\right), \quad \frac{\partial U(x)}{\partial x_i} = O\left(\frac{1}{|x|^2}\right). \tag{11}
\]

Let us formulate the uniqueness theorem of a solution of problems \((1,1)^\pm, (1,2)^\pm, (2,1)^\pm, (2,2)^\pm, (3)\) (see [1]).

**Theorem 1.** The problems \((1,1)^\pm, (1,2)^\pm, (2,1)^\pm, (2,2)^\pm, (3)\) at best have one regular solution. The difference of two regular solutions of the problem \((2,1)^+\) or \((2,2)^+\) is in the set \(\text{span}(A_1, ..., A_6)\), i.e. represented in the form

\[
\sum_{k=1}^{6} c_k A_k \quad (c_k = \text{const})
\]

where

\[
A_k = (\delta_{k1}, \delta_{k2}, \delta_{k3}, 0) \quad (k = 1, 2, 3) \quad \text{and} \quad A_{k+3} = \left(\sum_{l=1}^{3} \varepsilon_{k1l} x_l, \sum_{l=1}^{3} \varepsilon_{k2l} x_l, \sum_{l=1}^{3} \varepsilon_{k3l} x_l, 0\right),
\]

\(\varepsilon_{kjl}\) — symbol Levi-Civita.

The uniqueness theorems for the external boundary value problems are valid only under some restrictions of the class of solutions at infinity [1,4,5]. These restrictions arose naturally from the Green formulas and consist in the requirement that both the solution and its derivatives vanish at infinity (see (11)).

In this paper we will prove the following uniqueness theorem.

**Theorem 2.** The external boundary value problems \((1,1)^-, (1,2)^-, (2,1)^-, (2,2)^-\) and the general contact problem \((3)\) at best have one solution in the class of functions \(U\) satisfying the conditions

\[
U \in C^2(\Omega^-) \cap C^1(\overline{\Omega^-})
\]

and in a neighbourhood of infinity

\[
U_i(x) = o(1) \quad (i = 1, 2, 3, 4). \tag{12}
\]

First we prove the following theorem of the asymptotic representation of a solution of the homogeneous system \(B(\partial_x)U(x) = 0\) of (3) denoted by (3)_0.

**Theorem 3.** Let \(\Omega\) be a domain from \(\mathbb{R}^3\) containing infinity, \(U\) defined in \(\Omega\) and \(U \in C^2(\Omega)\). Let in a neighbourhood of \(|x| = +\infty\)

\[
U_i(x) = o\left(|x|^{p+1}\right) \quad (i = 1, 2, 3), \quad \text{and} \quad U_4(x) = o\left(|x|^p\right), \tag{13}
\]
where \( p \) is a non-negative integer. Then in a neighbourhood of \( |x| = +\infty \) the following asymptotic representation is valid:

\[
U_j(x) = U_j^{(0)}(x) + \sum_{|\alpha| \leq p} c_j^{(\alpha)} x^\alpha,
\]

where \( U_j^{(0)} \) is a regular solution of equation (3) in the domain \( \Omega \), i.e. \( U \in C^2(\Omega) \) and, in a neighborhood of \( |x| = +\infty \),

\[
|\partial^\beta U_j^{(0)}(x)| \leq \frac{C}{|x|^{1+|\beta|}} \quad (j = 1, 2, 3), \quad |\partial^\beta U_j^0(x)| \leq \frac{C}{|x|^{2+|\beta|}},
\]

where \( \beta = (\beta_1, \beta_2, \beta_3) \) is an arbitrary multiindex.

Theorem 3 can be used, in particular, for proof of Theorem 2. Indeed, let \( U \) be the difference of two solutions of the problem \((p, q)\) or (3) satisfying the conditions (12). Then \((p = 0)\) the representation

\[
U_j(x) = U_j^{(0)}(x) + C_j
\]

holds. From (14) and (12) we have \( C_j = 0 \) for \( j = 1, 2, 3, 4 \). Therefore \( U_j(x) = U_j^{(0)}(x) \). From Theorem 1 there follows \( U_j(x) = 0 \). Thus Theorem 2 is proved.

6. Proof of Theorem 3

Let \( \Omega \) be a domain in \( \mathbb{R}^3 \) containing a neighbourhood of infinity, \( x \in \Omega \), and \( \tau > 1 \) chosen such that

\[
x \in B\left(0, \frac{\tau}{8}\right) \quad \text{and} \quad \mathbb{R}^3 \setminus B\left(0, \frac{\tau}{8}\right) \subset \Omega.
\]

We write the Somigliana formula for the domain \( \Omega_r = B(0, \tau) \cap \Omega \). We will have

\[
U_j(x) = \int_{\partial \Omega} \left( U_i(y) R_{ik}(\partial_y, \nu) \Gamma_{kj}(y - x) - \Gamma_{kj}(y - x) R_{ki}(\partial_y, \nu) U_i(y) \right) d_y S
\]

\[+ \int_{\partial B(0, \tau)} \left( U_i(y) R_{ik}(\partial_y, \nu) \Gamma_{kj}(y - x) - \Gamma_{kj}(y - x) R_{ki}(\partial_y, \nu) U_i(y) \right) d_y S.
\]

Let

\[
U_j^{(0)}(x) = \int_{\partial \Omega} \left( U_i(y) R_{ik}(\partial_y, \nu) \Gamma_{kj}(y - x) - \Gamma_{kj}(y - x) R_{ki}(\partial_y, \nu) U_i(y) \right) d_y S
\]

\[T_j(x) = \int_{\partial B(0, \tau)} \left( U_i(y) R_{ik}(\partial_y, \nu) \Gamma_{kj}(y - x) - \Gamma_{kj}(y - x) R_{ki}(\partial_y, \nu) U_i(y) \right) d_y S.
\]

Then

\[
U_j(x) = U_j^{(0)}(x) + T_j(x).
\]

It is not difficult to prove that \( U^{(0)} \) is a solution of the equation (3). Let us establish the properties of the fundamental matrix

\[
\Gamma_{kj}(y - x) = \Gamma_{jk}(x - y).
\]
We have
\[
B_{ij}(\partial_x)U_j^{(0)}(x) = \int_{\partial\Omega} B_{kj}(\partial_x)U_i(y)R_{ik}(\partial_y, \nu)\Gamma_{kj}(y - x)\, d\nu S
- \int_{\partial\Omega} B_{ij}(\partial_x)\Gamma_{kj}(y - x)R_{ik}(\partial_y, \nu)U_i(y)\, d\nu S
= \int_{\partial\Omega} U_i(y)R_{ik}(\partial_y, \nu)B_{lj}(\partial_x)\Gamma_{jk}(x - y)\, d\nu S
- \int_{\partial\Omega} B_{ij}(\partial_x)\Gamma_{jk}(x - y)R_{ik}(\partial_y, \nu)U_i(y)\, d\nu S = 0.
\]

Now we will prove that \(U^{(0)}\) is a regular vector, i.e. in a neighbourhood of \(|x| = +\infty\) it admits the estimates (11). Moreover,
\[
|\partial^\alpha U_j^{(0)}(x)| \leq \frac{C}{|x|^{1+\alpha}} \quad (j = 1, 2, 3) \quad \text{and} \quad |\partial^\alpha U_4^{(0)}(x)| \leq \frac{C}{|x|^{2+\alpha}}.
\]
Indeed, this follows from (7). Let us establish the properties of the integral \(T_j(x)\) in a neighbourhood of infinity. If \(x \neq y\), then \(\Gamma_{kj}(y - x)\) is an analytic function. We represent \(\Gamma_{kj}(y - x)\) in a neighbourhood of the point \(y\) by the Taylor formula:
\[
\Gamma_{kj}(y - x) = \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|}x^\alpha}{\alpha!} \partial^\alpha \Gamma_{kj}(y) + S_{kj}(x, y) \quad (17)
\]
where \(p\) is an arbitrary non-negative integer, \(\alpha\) is a multiindex and \(0 < \theta < 1\). First we have to prove that
\[
\partial^\beta S_{kj}(x, y) = \sum_{|\alpha| = p+1} \frac{(-1)^{|\alpha|}x^\alpha}{\alpha!} \partial^{\alpha + \beta} \Gamma_{kj}(y - \theta_1 x), \quad (18)
\]
where \(\beta\) is an arbitrary multiindex and \(0 < \theta_1 < 1\). The differentiation of (17) gives
\[
\partial^\beta \Gamma_{kj}(y - x) = \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|}x^\alpha}{\alpha!} \partial^{\alpha + \beta} \Gamma_{kj}(y) + \partial^\beta S_{kj}(x, y). \quad (19)
\]
Indeed, using the Taylor formula we can represent \(\partial^\beta \Gamma_{kj}(y - x)\) in a neighbourhood of the point \(y\) as
\[
\partial^\beta \Gamma_{kj}(y - x) = \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|}x^\alpha}{\alpha!} \partial^{\alpha + \beta} \Gamma_{kj}(y) + S^{(1)}_{kj}(x, y) \quad (20)
\]
and
\[
S^{(1)}_{kj}(x, y) = \sum_{|\alpha| = p+1} \frac{(-1)^{|\alpha|}x^\alpha}{\alpha!} \partial^{\alpha + \beta} \Gamma_{kj}(y - \theta_1 x), \quad 0 < \theta_1 < 1. \quad (21)
\]
Therefore
\[ \partial^\alpha \eta_{k_j}(x,y) = S_{k_j}^{(1)}(x,y). \] (22)

By virtue of (22), (21), (20) and (19) we have (18).

We will estimate \( T_j(x) \) in a neighbourhood of \( |x| = +\infty \). But for all \( y \in \partial B(0,\tau) \) \((|y| = \tau)\) and for \( x \in B\left(0, \frac{\tau}{8}\right) \) \((|x| < \frac{\tau}{8}, 0 < \theta_1 < 1)\), we have
\[ |y - \theta_1 x| \geq \frac{7\tau}{8} = \frac{7|y|}{8}. \]

Hence by virtue of (7) we obtain the estimates
\[
|\partial^{\alpha + \beta} \Gamma_{k_j}(y - \theta_1 x)| \leq C_{\alpha, \beta}(x) |y - \theta_1 x|^{-1-|\alpha + \beta|} \\
\leq C_{\alpha, \beta}(x) |y|^{-2-|\beta|} \\
|\partial^{\alpha + \beta} \Gamma_{k_4}(y - \theta_1 x)| \leq C_{\alpha, \beta}(x) |y - \theta_1 x|^{-2-|\alpha + \beta|} \\
\leq C_{\alpha, \beta}(x) |y|^{-3-|\beta|} \\
|\partial^{\alpha + \beta} \Gamma_{k_5}(y - \theta_1 x)| \leq C_{\alpha, \beta}(x) |y|^{-3-|\beta|} \\
|\partial^{\alpha + \beta} \Gamma_{k_6}(y - \theta_1 x)| \leq C_{\alpha, \beta}(x) |y|^{-n-|\beta|}
\]
where \( n \) is an arbitrary non-negative integer. Hence we obtain the estimates
\[
|\partial^\alpha \eta_{k_j}(x,y)| \leq C_{\alpha, \beta}(x) |y|^{-2-|\beta|} \\
|\partial^\alpha \eta_{k_j}(x,y)| \leq C_{\alpha, \beta}(x) |y|^{-3-|\beta|} \\
|\partial^\alpha \eta_{k_4}(x,y)| \leq C_{\alpha, \beta}(x) |y|^{-n-|\beta|}
\]

The estimates (23) and (9) imply the following ones:
\[
|R_{ik}(\partial_\nu, \nu) S_{k_j}(x,y)| \leq C(x) |y|^{-3-\nu} \\
|\partial_\nu S_{k_j}(x,y)| \leq C(x) |y|^{-4-\nu}
\]

Let us now turn to the representation (15). We write
\[
T_j(x) = \int_{\partial B(0,\tau)} \left( U_i(y) R_{ik}(\partial_\nu, \nu) \left( \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|} x^\alpha}{\alpha!} \partial^\alpha \Gamma_{k_j}(y) + S_{k_j}(x,y) \right) \right) d\nu S \\
= \sum_{|\alpha| \leq p} C^{(\alpha)}_j(\tau) x^\alpha + L_j(p, \tau, x),
\]
where
\[
C^{(\alpha)}_j(\tau) = \frac{(-1)^{|\alpha|}}{\alpha!} \int_{\partial B(0,\tau)} \left( U_i(y) R_{ik}(\partial_\nu, \nu) \partial^\alpha \Gamma_{k_j}(y) \right) \\
\cdot \left( \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|} x^\alpha}{\alpha!} \partial^\alpha \Gamma_{k_j}(y) + S_{k_j}(x,y) \right) R_{ki}(\partial_\nu, \nu) U_i(y) d\nu S
\]
\[
L_j(p, \tau, x) = \int_{\partial B(0,\tau)} \left( U_i(y) R_{ik}(\partial_\nu, \nu) S_{k_j}(x,y) \right) \\
\cdot \left( \sum_{|\alpha| \leq p} \frac{(-1)^{|\alpha|} x^\alpha}{\alpha!} \partial^\alpha \Gamma_{k_j}(y) + S_{k_j}(x,y) \right) R_{ki}(\partial_\nu, \nu) U_i(y) d\nu S.
\]
We have to show that in the representation (24) the coefficients $C_j^{(\alpha)}(\tau)$ are independent of $\tau$. Indeed, let $\tau_1 > \tau$ and apply Green's formula (10) to the vectors

$$U = (U_1, U_2, U_3, U_4) \quad \text{and} \quad V = (\partial^a \Gamma_{1j}, \partial^a \Gamma_{2j}, \partial^a \Gamma_{3j}, \partial^a \Gamma_{4j})$$

in the domain $B(0, \tau_1) \setminus B(0, \tau)$. When $z \in B(0, \tau_1) \setminus B(0, \tau)$, we have

$$B_{ki}(\partial_z) V_i(z) = B_{ki}(\partial_z) \partial^a \Gamma_{ij}(z) = \partial^a B_{ki}(\partial_z) \Gamma_{ij}(z) = 0$$

and thus the volume integrals vanish in (10). Therefore we obtain

$$\int_{\partial B(0, \tau)} \left( \partial^a \Gamma_{ij}(y) R_{ik}(\partial_y, \nu) U_k(y) - U_k(y) R_{ki}(\partial_y, \nu) \partial^a \Gamma_{ij}(y) \right) d\nu S = 0$$

Here the normals to $\partial B(0, \tau)$ and $\partial B(0, \tau_1)$ are assumed to be external with respect to $B(0, \tau)$ and $B(0, \tau_1)$, respectively. The above equality shows that (see (25)) $C_j^{(\alpha)}(\tau) = C_j^{(\alpha)}(\tau_1)$. Now (24) implies that $L_j(p, \tau, x)$ is independent of $\tau$, too.

Now we will prove that if (13) is fulfilled, then

$$\lim_{\tau \to \infty} L_j(p, \tau, x) = 0. \quad (27)$$

On account of (27), (24) and (16), we obtain

$$U_j(x) = U_j^{(0)}(x) + T_j(x) = U_j^{(0)}(x) + \sum_{|\alpha| \leq p} C_j^{(\alpha)} x^\alpha. \quad (28)$$

Thus, if we prove (27), we will obtain (28).

Let $w \in C^\infty(\mathbb{R}^3)$ be a real function possessing the properties

$$w(y) = 1 \quad \text{for} \quad \frac{1}{2} \leq |y| \leq 2, \quad w(y) = 0 \quad \text{for} \quad |y| < \frac{1}{3}, \quad |y| > 3.$$  

Then the function $w^{(\tau)}(y) = w \left( \frac{y}{\tau} \right)$ possesses the properties:

$$w^{(\tau)}(y) = 1 \quad \text{for} \quad \frac{1}{2} \leq |y| \leq 2 \tau, \quad w^{(\tau)}(y) = 0 \quad \text{for} \quad |y| < \frac{\tau}{3}, \quad |y| > 3 \tau.$$  

Obviously, $b_\alpha = \sup_{\mathbb{R}^3} |\partial^\alpha w(y)| < +\infty$ and, therefore,

$$|\partial^\alpha w^{(\tau)}(y)| = \left| \frac{1}{\tau^{|\alpha|}} (\partial^\alpha w) \left( \frac{y}{\tau} \right) \right| \leq b_\alpha \tau^{-|\alpha|}. \quad (29)$$

Introduce the notation

$$S^{(\tau)}_{kj}(x, y) = w^{(\tau)}(y) S_{kj}(x, y).$$
Then $\text{S}^{(r)}_{kj}$ will have the properties:

$$
\begin{align*}
&\text{I}_{kj} \text{y} = 0, \\
& R_{ik}(\partial_y, \nu)S^{(r)}_{kj}(x, y) = 0 \quad \text{for all } y \in \partial B(0, \frac{\tau}{4}) \\
& S^{(r)}_{kj}(x, y) = S_{kj}(x, y), \\
& R_{ik}(\partial_y, \nu)S^{(r)}_{kj}(x, y) = R_{ik}(\partial_y, \nu)S_{kj}(x, y) \quad \text{for all } y \in \partial B(0, \tau).
\end{align*}
$$

(30)

Hence by virtue of (26) and (30), we obtain

$$
L(p, \tau, x) = \int_{\partial B(0,\tau) \Delta \partial B(0,\frac{\tau}{4})} (U_i(y)R_{ik}(\partial_y, \nu)S^{(r)}_{kj}(x, y) - S^{(r)}_{kj}(x, y)R_{ki}(\partial_y, \nu)U_i(y))dyS
$$

$$
= \int_{B(0,\tau) \Delta B(0,\frac{\tau}{4})} (U_i(z)B_{ik}(\partial_z)S^{(r)}_{kj}(x, z) - S^{(r)}_{kj}(x, z)B_{ki}(\partial_z)U_i(z))dz
$$

$$
= \int_{B(0,\tau) \Delta B(0,\frac{\tau}{4})} U_i(z)B_{ik}(\partial_z)S^{(r)}_{kj}(x, z)dz.
$$

On account of (23), using the above estimate for $\partial^aw^{(r)}$ (see (13) and (29)) we obtain

$$
U_i(z)B_{ik}(\partial_z)S^{(r)}_{kj}(x, z) = o(\tau^{-3}) \quad \text{for all } z \in B(0, \tau) \Delta B(0, \frac{\tau}{4}).
$$

Thus Theorem 3 is proved.

References


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